

Question Number	Answer		Mark
1(a)(i)	Calculation of average time period [accept average time for 10T] Use of $f = \frac{1}{T}$ $f = 1.5 \text{ Hz}$ Example of calculation $T = \frac{t_1 + t_2 + t_3}{30} = \frac{(6.2 + 6.6 + 6.9)\text{s}}{30} = 0.657 \text{ s}$ $f = \frac{1}{0.657 \text{ s}} = 1.52 \text{ Hz}$	(1) (1) (1)	3
1(a)(ii)	Force (or acceleration): proportional to displacement from equilibrium position always acting towards the equilibrium position Or always in the opposite direction to the displacement [accept rest/centre point for “equilibrium position”] [both marks can be gained from an equation with terms clearly defined including a correct reference to the negative sign]	(1) (1)	2
1(b)	There is (large) drag force [accept air resistance for drag] Producing a deceleration Or the oscillation is (heavily) damped Or energy is transferred/removed from the system [e.g. transferred to the surroundings.] [Do not accept “lost” for “transferred”]	(1) (1)	2
1(c)	Resonance Driven at a frequency equal/near the natural frequency of the wings [accept their answer to (a) as a numerical value] [for “driven” accept “forced/made to oscillate”]	(1) (1)	2
	Total for question		9

Question Number	Answer	Mark
2(a)	<p>Acceleration is:</p> <ul style="list-style-type: none"> (directly) proportional to displacement from equilibrium position (1) (always) acting towards the equilibrium position Or idea that acceleration is in the opposite direction to displacement (1) <p>[accept undisplaced point/fixed point/central point for equilibrium position]</p> <p>Or</p> <p>Force is:</p> <ul style="list-style-type: none"> (directly) proportional to displacement from equilibrium position (1) (always) acting towards the equilibrium position Or idea that force is a restoring force e.g. “in the opposite direction” (1) <p>[accept towards undisplaced point/fixed point/central point for equilibrium position]</p> <p>[An equation with symbols defined correctly is a valid response for both marks. e.g. $a \propto -x$ or $F \propto -x$]</p>	2
2(b)(i)	<p>Amplitude = 2.3 m [allow ± 0.1 m] (1)</p> <p>Time period = 24 hours [allow ± 0.5 hour] (1)</p> <p>[24 hours = 86 400 s]</p> <p><u>Example of calculation</u> Amplitude = $(6.1 \text{ m} - 1.5 \text{ m})/2 = 2.3 \text{ m}$ Period = $(48 \text{ hr} - 0 \text{ hr})/2 = 24 \text{ hr}$</p>	2
2(b)(ii)	<p>Use of $\omega = \frac{2\pi}{T}$ (1)</p> <p>Use of $v = (-)A\omega \sin \omega t$ [$v_{\text{max}} = \omega A$] (1)</p> <p>$v_{\text{max}} = 0.60 \text{ m hr}^{-1}$ (1)</p> <p><u>Example of calculation:</u> $\omega = \frac{2\pi}{T} = \frac{2\pi \text{ rad}}{24 \text{ hr}} = 0.262 \text{ rad hr}^{-1}$ $v_{\text{max}} = 0.262 \text{ rad hr}^{-1} \times 2.3 \text{ m} = 0.602 \text{ m hr}^{-1}$</p> <p>Or</p> <p>Attempt to calculate gradient with a max $\Delta t = 12$ hours, and max $\Delta x = 6$ m (1)</p> <p>Rate of change of depth in range $(0.54 - 0.66) \text{ m hr}^{-1}$ (1)</p> <p>Rate of change of depth in range $(0.57 - 0.63) \text{ m hr}^{-1}$ (1)</p> <p><u>Example of calculation</u> Rate of change of depth = $\frac{(6.5 - 1.0)}{(11.0 - 1.5)} = 0.57$</p>	3
2(b)(iii)	<p>Graph with correct shape [minus sine curve, at least 30 hours] (1)</p> <p>Same time period as graph given, constant amplitude (1)</p>	2
<p>Total for question</p>		9

Question Number	Answer	Mark
3(a)(i)	Use of $f=1/T$ (1)	2
	$f = 8 \text{ Hz}$ (1)	
	<u>Example of calculation</u> $f = \frac{1}{T} = \frac{1}{2 \times 0.0625 \text{ s}} = 8 \text{ Hz}$	
3(a)(ii)	At the equilibrium (position) / centre of the oscillation / mid-point (1)	1
3(a)(iii)	Use of $v_{\max}=2\pi fA$ OR $v_{\max}=\omega A$ (1)	2
	$v_{\max} = 2.5 \text{ ms}^{-1}$ [ecf for (a)(i), see table below] (1)	
	<u>Example of calculation</u> $v = 2\pi f A = 2\pi \times 8 \text{ s}^{-1} \times 5 \times 10^{-2} \text{ m} = 2.5 \text{ ms}^{-1}$	
3(b)(i)	Idea that the system is forced / driven into oscillation at / near its <u>natural</u> frequency (1)	2
	OR driver / forcing frequency is equal / near to <u>natural</u> frequency (1)	
	Leads to large/max energy transfer OR large/max/increasing amplitude (1)	
3(b)(ii)	Max 2	max 2
	◆ Rubber feet (deform and) absorb (vibration) energy (1)	
	◆ Reference to damping (1)	
	◆ Idea that energy is removed from system (1)	
	◆ Hence amplitude does not build up (1)	
Total for question		9

When marking 3(a)(iii) the table below may be helpful:

f/Hz		v/ms ⁻¹	Marks
8	5	2.5	2
16		5	2
8	10	5	1
16	1	10	1

Question Number	Answer	Mark
4(a)	Force (or acceleration): <ul style="list-style-type: none"> proportional to displacement from equilibrium/undisplaced/rest position (1) always acting towards the equilibrium/undisplaced/rest position Or always in the opposite direction to the displacement (1) 	2
4(b)(i)	Acceleration is a maximum at an extreme position (towards X) (1) Acceleration decreases to zero at X (1)	2
4(b)(ii)	Max 3 Total energy remains constant (1) (Elastic) potential energy is transferred to kinetic energy as string moves towards X (1) Kinetic energy is zero at an extreme position and a maximum at X (1) (Elastic) potential energy is a maximum at an extreme position and a minimum at X (1)	3
4(c)	Use of $\lambda = 2l$ (1) Use of $v = f\lambda$ (1) $f = 250 \text{ Hz}$ (1) <u>Example of calculation:</u> $\lambda = 2 \times 0.53 \text{ m} = 1.06 \text{ m}$ $f = v/\lambda = 270 \text{ m s}^{-1}/1.06 \text{ m} = 254.7 \text{ Hz}$	3
	Total for question	10

Question Number	Answer	Mark
5(a)	<p>(QWC – Work must be clear and organised in a logical manner using technical wording where appropriate)</p> <p>(Hooke’s Law:) for a spring, force is proportional to extension Or $F = k \Delta x$</p> <p>An extension of the spring causes a force towards the equilibrium position Or (resultant force towards the equilibrium position, so) $ma = -k \Delta x$</p> <p>Condition for shm is restoring force [acceleration] is proportional to displacement (from equilibrium position)</p> <p>[QWC question, so max 2 if equations given with no further explanation]</p>	<p>(1)</p> <p>(1)</p> <p>(1)</p> <p>3</p>
5(b)	<p>Use of $a = -\omega^2 x$</p> <p>Use of $T = \frac{2\pi}{\omega}$</p> <p>$T = 1.55$ (s)</p> <p>[Credit use of $F = k \Delta x$ and use of $T = 2\pi\sqrt{\frac{m}{k}}$ for first two marking points]</p> <p><u>Example of calculation:</u></p> $\omega = \sqrt{\frac{0.49 \text{ m s}^{-2}}{3.0 \times 10^{-2} \text{ m}}} = 4.04 \text{ s}^{-1}$ $T = \frac{2\pi}{4.04 \text{ s}^{-1}} = 1.55 \text{ s}$	<p>(1)</p> <p>(1)</p> <p>(1)</p> <p>3</p>
5(c)(i)	Damped / damping [Do not accept critical/heavy damping]	(1) 1
5(c)(ii)	Forced / driven	(1) 1
5(c)(iii)	<p>Resonance</p> <p>$f = 0.65 \text{ Hz}$ [accept s^{-1}] [0.625 Hz if show that value is used, 0.64 Hz if unrounded value used]</p> <p><u>Example of calculation:</u> $f = 1/1.55 \text{ s} = 0.645 \text{ Hz}$</p> <p>[allow 2nd mark if they use either their value from (b) or 1.6 s]</p>	<p>(1)</p> <p>(1)</p> <p>2</p>
5(d)	<p>(With a smaller mass baby) the natural frequency of oscillation would increase</p> <p>Or The natural frequency of the system would increase</p>	

	Or The periodic time of the system would decrease	(1)	
	Smaller mass baby would have to kick at a higher frequency (to force system into resonance) [accept larger mass baby would have to kick at a lower frequency]	(1)	2
	Total for question		12

Question Number	Answer		Mark
6(a)(i)	Resonance	(1)	1
6(a)(ii)	The vibrations from the engine/road surface/wheels must drive/force the tiger's head (to vibrate) at a frequency equal/close to its natural frequency	(1) (1)	
	Or Driver/forcing frequency Matches natural frequency	(1) (1)	2
6(b)(i)	Use of $\omega = \frac{2\pi}{T}$ Use of $a_{\max} = \omega^2 A$ Amplitude = 2×10^{-2} m <u>Example of calculation</u> $\omega = \frac{2\pi}{0.8 \text{ s}} = 7.85 \text{ (rad)s}^{-1}$ $A = \frac{1.2 \text{ ms}^{-2}}{(7.85 \text{ s}^{-1})^2} = 1.95 \times 10^{-2} \text{ m}$	(1) (1) (1)	3
6(b)(ii)	Correct shape and phase (in antiphase with acceleration) for graph Amplitude (ecf from (b)(i)) and a time marked on axes	(1) (1)	2
	Total for question		8