

Question Number	Scheme	Marks
1.	<p>Work done by force = <math>\begin{pmatrix} 1 \\ 2 \\ -2 \end{pmatrix} \cdot \mathbf{AB}</math></p> <p>Attempt at equating work done to KE</p> $\begin{pmatrix} 1 \\ 2 \\ -2 \end{pmatrix} \cdot \begin{pmatrix} \lambda \\ 2\lambda \\ 0 \end{pmatrix} \text{ or } \begin{pmatrix} 1 \\ 2 \\ -2 \end{pmatrix} \cdot \begin{pmatrix} x-2 \\ y+2 \\ z+3 \end{pmatrix} = \frac{1}{2}(0.1)5^2$ <p>Solving for <math>\lambda</math> (<math>\lambda = 0.25</math>) or forming sufficient equations in <math>x, y</math> [e.g. <math>x + 2y = -0.75</math>, <math>y + 2 = 2(x - 2)</math>]</p> <p>Method to find <b>OB</b></p> $[\mathbf{OB} = \begin{pmatrix} 2 \\ -2 \\ -3 \end{pmatrix} + \lambda \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix} \text{ or solving for } x, y]$ <p><b>OB</b> = <math>2\frac{1}{4}\mathbf{i} - 1\frac{1}{2}\mathbf{j} - 3\mathbf{k}</math> <span style="float: right;">any form</span></p>	<p>M1</p> <p>M1</p> <p>A1</p> <p>M1</p> <p>M1</p> <p>A1</p> <p style="text-align: right;"><b>(6 marks)</b></p>
Alt.	<p>Non-vector approach:</p> <p><math> F  \cos \theta = ma</math> applied; <span style="float: right;"><math>[a = 10\sqrt{5}]</math></span></p> <p>Method to find “s”: <math>5^2 = 2(10\sqrt{5})s</math> <span style="float: right;"><math>[s = \frac{\sqrt{5}}{4}]</math></span></p> <p>Finding <math>\lambda</math> <span style="float: right;">M1</span></p> <p>Method to find <b>OB</b> <span style="float: right;">M1 A1</span></p>	<p>M1</p> <p>M1 A1</p> <p>M1</p> <p>M1 A1</p>

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2. (a)	<p><i>Integrating factor approach:</i></p> $IF = e^{\int 1 dt} = e^t$ <p>Multiplying through <math>\Rightarrow \frac{d}{dt}(\mathbf{r}e^t) = (\mathbf{i} - \mathbf{j})e^{-t}</math></p> <p>Integrating <math>\Rightarrow \mathbf{r}e^t = -(\mathbf{i} - \mathbf{j})e^{-t} (+ \mathbf{c})</math></p> <p>Using <math>\mathbf{r} = \mathbf{0}</math>, <math>t = 0</math> to find <math>\mathbf{c}</math> [<math>\mathbf{c} = \mathbf{i} - \mathbf{j}</math>]</p> $\Rightarrow \mathbf{r} = -(\mathbf{i} - \mathbf{j})e^{-2t} + (\mathbf{i} - \mathbf{j})e^{-t}$	<p>B1</p> <p>M1A1</p> <p>M1 A1 ft</p> <p>M1</p> <p>A1 (7)</p>
(b)	<p>Writing <math>\mathbf{r} = f(t)\mathbf{i} + g(t)\mathbf{j}</math> or <math>x = f(t)</math>, <math>y = g(t)</math> and attempt to eliminate <math>t</math></p> $y = -x$	<p>M1</p> <p>A1 (2)</p> <p><b>(9 marks)</b></p>
Alt. (a)	<p>AE <math>m + 1 = 0 \Rightarrow \mathbf{r} = \mathbf{A}e^{-t}</math> [Form of PI: <math>\mathbf{r} = \mathbf{B}e^{-2t}</math>]</p> <p>Equation for PI: <math>-2e^{-2t}\mathbf{B} + \mathbf{B}e^{-2t} = (\mathbf{i} - \mathbf{j})e^{-2t}</math></p> $\mathbf{B} = -(\mathbf{i} - \mathbf{j})$ <p>General Solution: <math>\mathbf{r} = \mathbf{A}e^{-t} + (-\mathbf{i} + \mathbf{j})e^{-2t}</math></p> <p>Using <math>\mathbf{r} = \mathbf{0}</math>, <math>t = 0</math> to find <math>\mathbf{A}</math></p> $\mathbf{r} = (\mathbf{i} - \mathbf{j})e^{-t} + (-\mathbf{i} + \mathbf{j})e^{-2t}$	<p>B1</p> <p>M1 A1</p> <p>A1 ft</p> <p>M1</p> <p>M1</p> <p>A1 (7)</p>

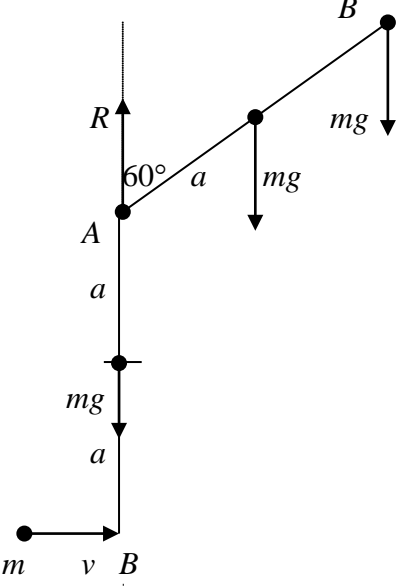
(ft = follow through mark)

Question Number	Scheme	Marks
3. (a)	$\mathbf{R} = \begin{pmatrix} 4 \\ -2 \\ 0 \end{pmatrix} + \begin{pmatrix} 4 \\ 2 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ -2 \\ 1 \end{pmatrix} + \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 8 \\ 0 \\ 2 \end{pmatrix} \quad \text{or} \quad 8\mathbf{i} + 2\mathbf{k}$	M1 A1 (2)
(b)	<p>Finding one of <math>\begin{pmatrix} 3 \\ 0 \\ 0 \end{pmatrix} \times \begin{pmatrix} 4 \\ -2 \\ 0 \end{pmatrix}</math>, <math>\begin{pmatrix} 3 \\ 4 \\ 0 \end{pmatrix} \times \begin{pmatrix} 4 \\ 2 \\ 0 \end{pmatrix}</math>, <math>\begin{pmatrix} 0 \\ 0 \\ 3 \end{pmatrix} \times \begin{pmatrix} 0 \\ -2 \\ 1 \end{pmatrix}</math>, <math>\begin{pmatrix} 0 \\ 4 \\ 3 \end{pmatrix} \times \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix}</math></p> $= \begin{pmatrix} 0 \\ 0 \\ -6 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ -10 \end{pmatrix}, \begin{pmatrix} 6 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} -2 \\ 0 \\ 0 \end{pmatrix}$ <p>[A1 one correct, A2 at least three correct]</p> <p>Resultant = <math>\begin{pmatrix} 4 \\ 0 \\ -16 \end{pmatrix}</math> any form</p>	M1 A2, 1, 0 M1 A1 (5)
(c)	$\mathbf{F} = -8\mathbf{i} - 2\mathbf{k}$	B1ft (1)
(d)	<p>For equilibrium <math>\mathbf{r} \times \begin{pmatrix} -8 \\ 0 \\ -2 \end{pmatrix} = -\begin{pmatrix} 4 \\ 0 \\ -16 \end{pmatrix}</math> or equivalent</p> $\mathbf{PX} = \begin{pmatrix} 0 \\ \lambda \\ 0 \end{pmatrix} \Rightarrow \mathbf{r} \times \begin{pmatrix} -8 \\ 0 \\ -2 \end{pmatrix} = \begin{pmatrix} -2\lambda \\ 0 \\ 8\lambda \end{pmatrix}$ <p>Finding <math>\lambda</math> ; <math>PX = 2.</math></p>	M1 M1 A1 ft M1; A1 (5) <b>(13 marks)</b>

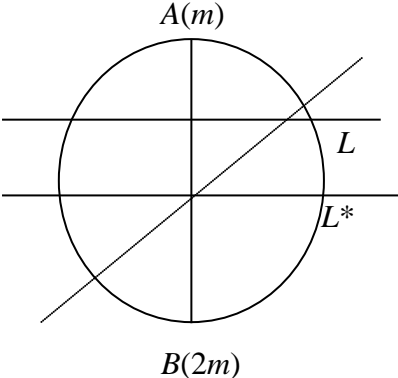
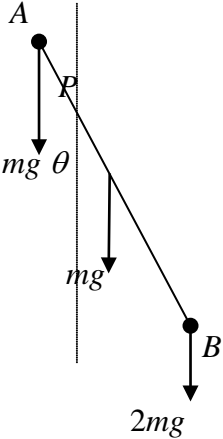
(ft = follow through mark)

Question Number	Scheme	Marks
4. (a)	$(m + \delta m)(v + \delta v) + (-\delta m)(v - U) - mv = -kv \delta t$ $\Rightarrow m \frac{dv}{dt} + U \frac{dm}{dt} = -kv$ $m = M - \lambda t$ $\Rightarrow (M - \lambda t) \frac{dv}{dt} = \lambda U - kv$ $\Rightarrow \frac{dv}{dt} = \frac{\lambda U - kv}{M - \lambda t} \quad (*)$	M1A1A1 A1 B1 M1 A1 cso (7)
	<p>(b) Separating variables: <math>\int \frac{dv}{U - v} = \int \frac{10}{M - 10t} dt</math> or equivalent M1</p> <p>Integrating: <math>\ln(U - v) = \ln(M - 10t) + c</math> M1 A1</p> <p>Using limits correctly: <math>[\ ]_v^0 = [\ ]_t^0</math> applied or <math>t = 0, v = 0</math> to find “c” M1</p> <p style="text-align: right;"><math>[ c = \ln\left(\frac{U}{M}\right) ]</math></p> <p>Complete method to find <math>v</math> <math>[\ln\left(\frac{U}{U - v}\right) = \ln\left(\frac{M}{M - 10t}\right)]</math> M1</p> <p style="text-align: center;"><math>v = \frac{10Ut}{M}</math></p> <p style="text-align: right;">A1 (6)</p> <p style="text-align: right;"><b>(13 marks)</b></p>	

(cso = correct solution only)

Question Number	Scheme	Marks
<p>5. (a)</p> 	<p> <math>I_A = \left\{ \frac{4}{3} ma^2 + m(2a)^2 \right\}</math>  <math>mv(2a) = I_A \omega = \frac{16ma^2}{3} \omega</math>  <math>\omega = \frac{3v}{8a}</math> *      no wrong working seen                      Gain in PE = <math>mg 3a(1 + \cos 60^\circ)</math>                      Attempt at <math>\frac{1}{2} I \omega^2 = \text{gain in PE}</math>  <math>\frac{1}{2} \left( \frac{16ma^2}{3} \right) \left( \frac{3v}{8a} \right)^2 = mg 3a(1 + \cos 60^\circ)</math>                      Finding <math>v</math>      <math>v = \sqrt{12ga}</math> </p> <p>(c)</p> <p>Acceleration of C of G = <math>\left( \frac{3}{2} a \omega^2 \right)</math>  <math>R - 2mg = mr \omega^2 ; = 2m \left( \frac{3}{2} a \omega^2 \right)</math>                      Substitution of <math>\omega</math> and <math>v</math> and finding <math>R = \dots</math>  <math>R = \frac{113}{16} mg</math> </p>	<p>M1 A1                      M1 A1ft                      A1 cso (5)                      M1 A1                      M1                      A1 ft                      M1 A1 (6)                      B1                      M1 A1                      M1                      A1 (5)  <b>(16 marks)</b></p>

(cso = correct solution only; ft = follow through mark)

Question Number	Scheme	Marks
6 (a)	$(\delta I) = (\rho)2\pi r \delta r \times r^2$ <p>Using <math>(\rho) = \frac{m}{\pi a^2}</math></p> <p>Completion: <math>I = \frac{2m}{a^2} \left[ \frac{r^4}{4} \right]_0^a = \frac{1}{2} ma^2</math> (*)</p>  <p>Disc: Use of <math>\perp r</math> axis theorem to find <math>I_{L^*}</math></p> $I_{L^*} = \frac{1}{2} \left( \frac{1}{2} ma^2 \right) = \frac{1}{4} ma^2$ <p>Use of parallel axis theorem</p> $I_L = \frac{1}{4} ma^2 + m \left( \frac{a}{2} \right)^2 = \frac{1}{2} ma^2$ <p>For loaded disc: <math>I = \frac{1}{2} ma^2 + m \left( \frac{a}{2} \right)^2 + 2m \left( \frac{3a}{2} \right)^2 = \frac{21}{4} ma^2</math> (*)</p>	<p>M1</p> <p>M1</p> <p>M1 A1 (4)</p> <p>M1</p> <p>A1</p> <p>M1 A1</p> <p>M1 A1 cso (6)</p>
(c)	$I \ddot{\theta} = \left\{ mg \left( \frac{a}{2} \right) \sin \theta - mg \left( \frac{a}{2} \right) \sin \theta - 2mg \left( \frac{3a}{2} \right) \sin \theta \right\}$ <p>[A1 for signs, A1 “terms”]</p> $\left[ \frac{21}{4} ma^2 \ddot{\theta} = -3mga \sin \theta \right]$ <p>For small angles <math>\theta \approx \sin \theta \Rightarrow</math></p> $\frac{21}{4} ma^2 \ddot{\theta} = -3mga \theta$ $\ddot{\theta} = -\frac{4g}{7a} \theta$ <p><math>\Rightarrow</math> SHM with <math>\omega^2 = \frac{4g}{7a}</math></p> <p>Time = <math>\frac{\pi}{\omega}</math> ; <math>= \pi \sqrt{\frac{7a}{4g}}</math> or <math>\frac{\pi}{2} \sqrt{\frac{7a}{g}}</math></p> 	<p>M1 A1 A1</p> <p>M1</p> <p>A1 ft</p> <p>M1</p> <p>M1; A1 (8)</p> <p><b>(18 marks)</b></p>

(cao = correct answer only; ft = follow through mark; (\*) indicates final line is given on the paper)