Mechanics 3

Solution Bank



Chapter review



 $(\uparrow) 2T \cos \theta = mg \qquad (1)$

By Hooke's law

$$T = \frac{15mgx}{16a}$$
(2)

$$\sin\theta = \frac{a}{a+x} \tag{3}$$

a If
$$\cos \theta = \frac{4}{5}$$
, $T = \frac{5mg}{8}$ from (1)
so, $\frac{5mg}{8} = \frac{15mgx}{16a}$ from (2)
 $\frac{2a}{3} = x$
And from (3)
 $\sin \theta = \frac{a}{a + \frac{2a}{3}} = \frac{3}{5}$

which is consistent with $\cos\theta = \frac{4}{5}$.

b Work done on particle = overall gain in energy = P.E. gain - E.P.E. loss

$$PM = (a+x)\cos\theta$$

= $\left(a + \frac{2a}{3}\right)\frac{4}{5}$
= $\frac{4a}{3}$
∴ P.E. gain = $mg\frac{4a}{3}$
E.P.E. loss = initial E.P.E. – final E.P.E.
= $\frac{15mg}{16 \times 2a} \left(2 \times \left(\frac{2a}{3}\right)^2 - 0^2\right)$
= $\frac{15mg \times 2 \times 4a^2}{16 \times 2a \times 9}$
= $\frac{5mga}{12}$
So, work done = $\frac{4mga}{3} - \frac{5mga}{12}$
= $\frac{mga}{12}(16-5)$
= $\frac{11mga}{12}$

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2 Let *l* be the natural length of the spring.Let λ be the modulus of the spring.



(\uparrow) T = Wby Hooke's law,

$$T = \frac{\lambda a}{l}$$

. $W = \frac{\lambda a}{l}$ i.e. $\frac{W}{a} = \frac{\lambda}{l}$

Using conservation of energy,

P.E. loss of W = E.P.E. gain of spring

x

$$W\left(\frac{3a}{2} + x\right) = \frac{\lambda x^2}{2l}$$

so, $W\left(\frac{3a}{2} + x\right) = \frac{Wx^2}{2a}$
 $3a^2 + 2ax = x^2$
 $0 = x^2 - 2ax - 3a^2$
 $0 = (x - 3a)(x + a)$
 $\therefore x = 3a \text{ or } -a$

 \therefore maximum compression is 3a



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4 Triangle *ABP* is a 3,4,5 triangle, so angle *APB* is a right angle.

$$\cos\theta = \frac{3}{5} \text{ and } \sin\theta = \frac{4}{5}$$

$$(\uparrow) T_1 \sin\theta + T_2 \cos\theta = mg$$

$$\frac{4}{5}T_1 + \frac{3}{5}T_2 = mg$$

$$4T_1 + 3T_2 = 5mg \quad (1)$$

$$(\rightarrow) T_1 \cos\theta = T_2 \sin\theta$$

$$\frac{3}{5}T_1 = \frac{4}{5}T_2$$

$$T_1 = \frac{4}{3}T_2 \quad (2)$$
Substituting from (2) into (1):



1 /

$$\frac{16}{3}T_2 + 3T_2 = 5mg$$
$$25T_2 = 15mg$$
$$T_2 = \frac{3mg}{5}$$

From Hooke's law,

$$T_{2} = \frac{\lambda x}{l} = \frac{\lambda(a-l)}{l}$$
$$\frac{3mg}{5} = \lambda \left(\frac{a}{l} - 1\right)$$
$$\frac{3mg}{5\lambda} + 1 = \frac{a}{l}$$
$$\frac{3mg + 5\lambda}{5\lambda} = \frac{a}{l}$$
$$l = \frac{5\lambda a}{3mg + 5\lambda}$$



Work done against friction = overall loss in energy

$$= \text{E.P.E. loss} - \text{K.E. gain}$$

$$\frac{1}{5} mg \frac{3a}{2} = \frac{5 mg \left(\frac{a}{2}\right)^2}{2a} - \frac{1}{2}mV^2$$

$$\frac{3ag}{5} = \frac{5ag}{4} - V^2$$

$$V^2 = \frac{5ag}{4} - \frac{3ag}{5} = \frac{ag(25 - 12)}{20}$$

$$V = \sqrt{\frac{13ag}{20}}$$





Friction will be the same. Assume string is still slack when ball comes to rest.

Work done against friction = K.E. loss

$$\frac{1}{5}mg d = \frac{1}{2}m\left(\frac{2V}{5}\right)^2 = \frac{1}{2}m\frac{4V^2}{25}$$
$$\frac{1}{5}gd = \frac{1}{2} \times \frac{4}{25} \times \frac{13ag}{20}$$
$$d = \frac{13a}{50}$$

As *d* is less than *a*, the assumption that the string is still slack is valid.

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$$(\uparrow)R = mg \quad (\rightarrow)\mu R = T$$
$$\mu mg = T$$

1

by Hooke's law,

$$T = \frac{2mg}{l} \times \frac{l}{3} = \frac{2mg}{3}$$

$$\therefore \qquad \mu mg = \frac{2mg}{3}$$

$$\mu = \frac{2}{3}$$

b
$$\mu = \frac{2}{3}$$

Work done against friction = overall loss in energy

1

= E.P.E. loss - K.E. gain

$$\frac{2}{3}mgl = \frac{2mgl^2}{2l} - \frac{1}{2}mv^2$$
$$\frac{1}{2}v^2 = gl - \frac{2}{3}gl = \frac{1}{3}gl$$
$$v^2 = \frac{2}{3}gl$$
$$v = \sqrt{\frac{2gl}{3}}$$

c String is now slack.

Work done against friction = K.E. loss

$$\frac{2}{3}mg d = \frac{1}{2}m \times \frac{2}{3}gl$$
$$d = \frac{1}{2}l$$

Total distance travelled is $\frac{3l}{2}$.



$$\operatorname{so}, \frac{T_2}{T_1} = \frac{\cos\theta}{\sin\theta}$$
$$\frac{\lambda x_2}{0.05} \times \frac{0.15}{\lambda x_1} = \frac{\cos\theta}{\sin\theta}$$
$$\frac{3x_2}{x_1} = \frac{\cos\theta}{\sin\theta}$$
i.e. $\frac{x_1}{x_2} = \frac{3\sin\theta}{\cos\theta}$ Using the answer to part **a**:
$$\frac{4\cos\theta - 3}{4\sin\theta - 1} = \frac{3\sin\theta}{\cos\theta}$$

 $3\sin\theta(4\sin\theta-1) = \cos\theta(4\cos\theta-3)$



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8 a



(\nearrow perpendicular to string)



b
$$(\rightarrow) T \sin \theta = 9.8$$

$$T = 9.8\sqrt{10}$$
$$\frac{14.7 \times x}{1} = 9.8\sqrt{10}$$
$$x = \frac{2\sqrt{10}}{3} \approx 2.108..$$

The extension is 2.1 m (2 s.f.).



Least force will be perpendicular to the string

$$(\nearrow) F = 3g \sin \theta$$
$$= \frac{3g}{\sqrt{10}}$$
$$= \frac{3g\sqrt{10}}{10}$$
$$= 9.297...$$

The least force is 9.3 N (2 s.f.).



a By conservation of energy,

K.E. gain + E.P.E. gain = P.E. loss

$$\frac{1}{2}mv^{2} + \left(\frac{mg}{4} \times \frac{x^{2}}{2a}\right) = mg \times 4a$$

$$BP = 5a (3, 4, 5 \text{ triangle})$$
So, $x = 4a$

$$\therefore \quad \frac{1}{2}mv^{2} + \left(\frac{mg}{4} \times \frac{16a^{2}}{2a}\right) = 4mga$$

$$v^{2} + 4ga = 8ga$$

$$v^{2} = 4ga$$

$$v = 2\sqrt{ga}$$

b
$$x = 4a: T = \frac{mg}{4} \times \frac{4a}{a}$$

= mg

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Challenge

We define the variables for the problem as in the following diagram;



maximum depth

a Now, applying conservation of elastic potential energy and gravitational potential energy, we find that:

$$mgd = \frac{1}{2} \cdot \frac{\lambda}{l} \cdot (d-l)^2$$
$$\Rightarrow mgld = \frac{\lambda}{2} (d^2 + l^2 - 2dl)$$
$$\Rightarrow \frac{2mgl}{\lambda} d = d^2 + l^2 - 2dl$$

Substituting $k = \frac{mgl}{\lambda}$ and rearranging, we see that:

$$d^{2} - 2(l+k)d + l^{2} = 0$$

$$\Rightarrow d = \frac{1}{2} \left(2(l+k) \pm 2\sqrt{(l+k)^{2} - l^{2}} \right)$$

$$\Rightarrow d = (l+k) \pm \sqrt{k^{2} + 2lk}$$

But we know that d must be larger than l, else the string wouldn't be taut when the maximum depth was reached, so we should take the positive square root, giving the result.

b i Suppose the jumper had an initial downwards velocity, *v*.

Then they would have an initial kinetic energy $\frac{1}{2}mv^2$ in the downwards direction, in addition to the initial GPE of *mgd*. So the distance the jumper falls increases.

ii If we included air resistance, the frictional force would do work on the jumper as they fell. Then the energy balance is GPE + EPE + Work done by friction = 0. This results in a reduced GPE, decreasing the maximum distance the jumper falls.