

1(a)(i)	MLT^{-2}	B1 1	Allow $kg\ ms^{-2}$
(ii)	$(T) = (MLT^{-2})^\alpha (L)^\beta (ML^{-1})^\gamma$ Powers of M: $\alpha + \gamma = 0$ of L: $\alpha + \beta - \gamma = 0$ of T: $-2\alpha = 1$ $\alpha = -\frac{1}{2}, \beta = 1, \gamma = \frac{1}{2}$	B1 M1 M2 A2 6	For ML^{-1} For three equations Give M1 for one equation Give A1 for one correct
(iii)	$kF_1^\alpha l_1^\beta \sigma^\gamma = kF_2^\alpha l_2^\beta \sigma^\gamma$ $F_1^{-\frac{1}{2}} l_1 = F_2^{-\frac{1}{2}} l_2$ OR $F^\alpha l^\beta$ is constant F is proportional to l^2 $F_2 = 90 \times \frac{2.0^2}{1.2^2}$ = 250 (N)	M1 A1 M1 A1 M1 A1 4	Equation relating F_1, F_2, l_1, l_2 or equivalent
(b)(i)	$\frac{2\pi}{\omega} = 0.01$ $\omega = 200\pi$ Maximum speed is $A\omega = 0.018 \times 200\pi$ = 11.3 (ms^{-1})	B1 M1 A1 3	Accept 3.6π
(ii)	Using $v^2 = \omega^2(A^2 - x^2)$ $8^2 = (200\pi)^2(0.018^2 - x^2)$ $x = 0.0127$ (m) OR $v = 3.6\pi \cos(200\pi t) = 8$ when $200\pi t = 0.785$ ($t = 0.001249$) $x = 0.018 \sin(200\pi t) = 0.018 \sin(0.785)$ = 0.0127	M1 M1 A1 A1 4 M1 A1 M1 A1	Substituting values <i>Condone the use of degrees in this part</i>

2 (a)	$\omega = \frac{2\pi}{2.4 \times 10^6} \quad (= 2.618 \times 10^{-6})$ <p>Acceleration $a = r\omega^2$ (or $\frac{v^2}{r}$) $= 2.604 \times 10^{-3}$</p> <p>Force is $ma = 7.5 \times 10^{22} \times 2.604 \times 10^{-3}$ $= 1.95 \times 10^{20}$ (N)</p>	B1 M1 M1 A1 4	<p>or $v = \frac{2\pi \times 3.8 \times 10^8}{2.4 \times 10^6} \quad (= 994.8)$</p> <p>M0 for $F - mg = ma$ etc Accept 1.9×10^{20} or 2.0×10^{20}</p>
(b)(i)	<p>Change in PE is $mg(3.5 - 4 \sin \theta)$</p> <p>By conservation of energy $\frac{1}{2}mv^2 = mg(3.5 - 4 \sin \theta)$ $v^2 = 68.6 - 78.4 \sin \theta$</p>	B1 M1 A1 3	<p>or as separate terms</p> <p>Accept $7g - 8g \sin \theta$</p>
(ii)	$0.2 \times 9.8 \sin \theta - R = 0.2 \times \frac{v^2}{4}$ $1.96 \sin \theta - R = 0.05(68.6 - 78.4 \sin \theta)$ $R = 5.88 \sin \theta - 3.43$	M1 M1 A1 E1 4	<p>Radial equation of motion (3 terms)</p> <p>Substituting from part (i)</p> <p>Correctly obtained</p>
(iii)	<p>When $\theta = 40^\circ$, $v^2 = 18.21$</p> <p>Radial acceleration is $\frac{v^2}{4} = 4.55 \text{ (ms}^{-2}\text{)}$</p> <p>Tangential acceleration is $9.8 \cos 40$ $= 7.51 \text{ (ms}^{-2}\text{)}$</p>	M1 A1 M1 A1 4	<p>or $0.2g \sin 40 - R = ma$</p> <p>Accept 4.5 or 4.6</p> <p>M0 for $a = mg \cos 40$ etc</p>
(iv)	<p>Leaves surface when $R = 0$</p> $\sin \theta = \frac{3.43}{5.88}$ $\theta = 35.7^\circ$	M1 M1 A1 cao 3	<p>Accept 36°, 0.62 rad</p>

3 (i)	$\frac{\lambda}{15} \times 0.8 = 12 \times 9.8$ $\lambda = 2205 \text{ (N)}$	M1 E1 2	
(ii)	$\frac{2205}{15} \times 5 - 12 \times 9.8 = 12a$ $a = 51.45 \text{ (ms}^{-2}\text{)}$	M1 A1 A1 3	Equation of motion including tension Accept 51 or 52
(iii)	Loss of EE is $\frac{1}{2} \times \frac{2205}{15} \times 5^2$ (=1837.5)	M1 A1	Calculating elastic energy
	By conservation of energy $12 \times 9.8 \times h = 1837.5$ $h = 15.625$ OA = $20 - h = 4.375$ (m)	M1 F1 A1 5	Equation involving EE and PE
	OR $12 \times 9.8 \times 5 + \frac{1}{2} \times 12 \times v^2 = 1837.5$ $v^2 = 208.25$ $0 = 208.25 - 2 \times 9.8 \times H$ $H = 10.625$ OA = $15 - H = 4.375$ (m)	M1 F1 A1	Equation involving EE, PE and KE
(iv)	$T = \frac{2205}{15}(0.8 + x)$ $12 \times 9.8 - \frac{2205}{15}(0.8 + x) = 12 \frac{d^2x}{dt^2}$ $\frac{d^2x}{dt^2} = -12.25x$	B1 M1 A1 E1 4	or $T = \frac{\lambda}{l}(x_0 + x)$ Equation of motion with three terms or $mg - \frac{\lambda}{l}(x_0 + x) = m \frac{d^2x}{dt^2}$ provided that $mg = \frac{\lambda}{l}x_0$ appears somewhere Correctly obtained <i>No marks for just writing</i> $-\frac{2205}{15}x = 12 \frac{d^2x}{dt^2}$ or just using <i>the formula</i> $\omega^2 = \frac{\lambda}{ml}$ <i>If x is clearly measured upwards, treat as a mis-read</i>
(v)	$x = 4.2 \cos(3.5t)$ Rope becomes slack when $x = -0.8$ $4.2 \cos(3.5t) = -0.8$ $t = 0.504$ (s)	M1 A1 M1 A1 4	For $\cos(\sqrt{12.25}t)$ or $\sin(\sqrt{12.25}t)$ Accept 0.50 or 0.51

<p>4 (i)</p>	$\int y \, dx = \int_0^2 (4 - x^2) \, dx = \left[4x - \frac{1}{3}x^3 \right]_0^2 \quad \left(= \frac{16}{3} \right)$ $\int xy \, dx = \int_0^2 x(4 - x^2) \, dx$ $= \left[2x^2 - \frac{1}{4}x^4 \right]_0^2 \quad (= 4)$ $\bar{x} = \frac{4}{\frac{16}{3}}$ $= 0.75$	<p>B1</p> <p>M1</p> <p>A1</p> <p>M1</p> <p>E1</p>	<p>Correctly obtained</p>
	$\int \frac{1}{2} y^2 \, dx = \int_0^2 \frac{1}{2} (16 - 8x^2 + x^4) \, dx$ $= \left[8x - \frac{4}{3}x^3 + \frac{1}{10}x^5 \right]_0^2 \quad \left(= \frac{128}{15} \right)$	<p>M1</p> <p>A1</p>	
	<p>OR</p> $\int yx \, dy = \int_0^4 y\sqrt{4-y} \, dy$ $= \left[-\frac{2}{3}y(4-y)^{\frac{3}{2}} - \frac{4}{15}(4-y)^{\frac{5}{2}} \right]_0^4$	<p>M1</p> <p>A1</p>	<p>Valid method of integration</p> <p>or $\left[-\frac{8}{3}(4-y)^{\frac{3}{2}} + \frac{2}{5}(4-y)^{\frac{5}{2}} \right]_0^4$</p>
	$\bar{y} = \frac{\frac{128}{15}}{\frac{16}{3}}$ $= 1.6$	<p>M1</p> <p>E1</p>	<p>Correctly obtained</p> <p>9 SR If $\frac{1}{2}$ is omitted, marks for \bar{y} are M1A0M0E0</p>
<p>(ii)</p>	$\bar{x} = \frac{12 \times 0 + 6.5 \times 0.75 + 6.5 \times 2.75}{12 + 6.5 + 6.5}$ $= \frac{22.75}{25} = 0.91$ $\bar{y} = \frac{12 \times 0 + 6.5 \times 1.6 + 6.5 \times 1.6}{25}$ $= \frac{20.8}{25} = 0.832$	<p>M1</p> <p>M1</p> <p>A1</p> <p>M1</p> <p>A1</p>	<p>For $6.5 \times 0.75 + 6.5 \times 2.75$</p> <p>Using $(\sum m)\bar{x} = \sum mx$</p> <p>Using $(\sum m)\bar{y} = \sum my$</p> <p>5</p>
<p>(iii)</p>	$\tan \theta = \frac{2 - 0.91}{4 - 0.832} \quad \left(= \frac{1.09}{3.168} \right)$ $\theta = 19.0^\circ$	<p>M1</p> <p>M1</p> <p>A1</p> <p>A1</p>	<p>For CM vertically below A</p> <p>For trig in a triangle containing θ, or finding the gradient of AG</p> <p>Correct expression for $\tan \theta$ or $\tan(90 - \theta)$</p> <p>Accept 0.33 rad</p> <p>4</p>