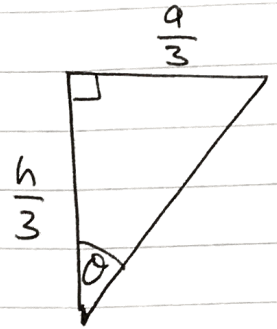
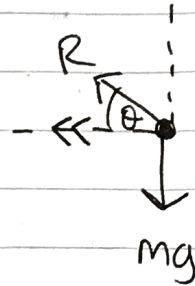
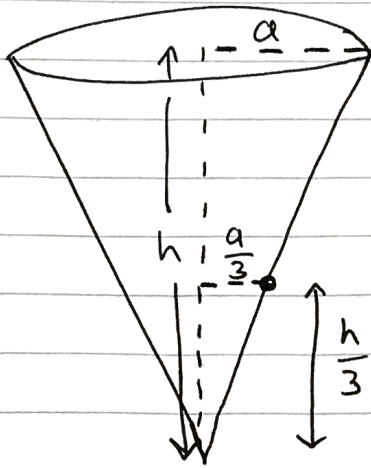


M3 June 2013(R) (MA)

Q1)



$$\tan \theta = \frac{a}{h}$$

$$\therefore \sin \theta = \frac{a}{\sqrt{a^2 + h^2}}$$

$$\& \cos \theta = \frac{h}{\sqrt{a^2 + h^2}}$$

$$R(\uparrow): R \sin \theta = mg$$

$$\frac{Ra}{\sqrt{a^2 + h^2}} = mg$$

$$\therefore R = \frac{mg \sqrt{a^2 + h^2}}{a}$$

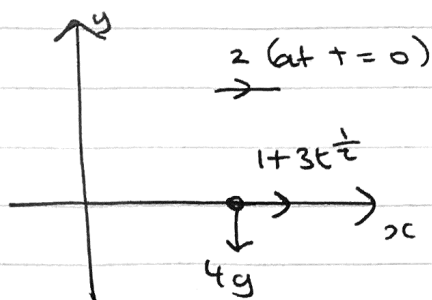
$$\overset{+}{\text{N2L (particle)}}: R \cos \theta = \frac{mv^2}{r}$$

$$\frac{r = \frac{a}{3}}{\underline{\quad}}: \left( \frac{mg \sqrt{a^2 + h^2}}{a} \right) \left( \frac{h}{\sqrt{a^2 + h^2}} \right) = \frac{mv^2}{\frac{a}{3}}$$

$$\Rightarrow \frac{gh}{a} = \frac{3v^2}{a}$$

$$\Rightarrow 3v^2 = gh \quad \therefore v^2 = \frac{gh}{3} \rightarrow v = \sqrt{\frac{gh}{3}}$$

Q2)



$$F = 1 + 3t^{\frac{1}{2}} = ma$$

$$1 + 3t^{\frac{1}{2}} = 4 \frac{dv}{dt}$$

$$\int 4 dv = \int 1 + 3t^{\frac{1}{2}} dt$$

$$4v = t + 3t^{\frac{3}{2}} \left(\frac{2}{3}\right) + c$$

$$4v = t + 2t^{\frac{3}{2}} + c$$

$$\underline{t=0, v=2}: 8 = c$$

$$\therefore 4v = t + 2t^{3/2} + 8$$

$$v = \frac{1}{4} (t + 2t^{3/2} + 8)$$

Work Done =  $\Delta KE$  from  $t=0$  to  $t=4$ .

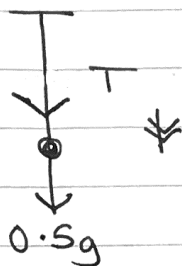
$$\underline{\text{at } t=0}: KE = 2v^2 = 2(4) = 8 \text{ J}$$

$$\underline{\text{at } t=4}: v = \frac{1}{4} (4 + 2(4)^{3/2} + 8) = 7 \text{ ms}^{-1}$$

$$\therefore KE = \frac{1}{2} (4)(7^2) = 98 \text{ J}$$

$$\Delta KE = (98 - 8) \text{ J} = \boxed{90 \text{ J}} = \text{Work Done by the force}$$

Q3a)



$$\downarrow \text{N2L (P)} : 0.5g + T = 0.5a$$

$$T = \frac{\lambda x}{l} = \frac{20(1)}{2} = 10$$

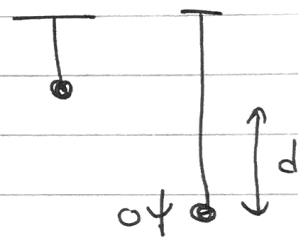
$$\frac{0.5g + 10}{0.5} = a = \boxed{29.8 \text{ ms}^{-2}}$$

b) Initially :

$$KE = 0$$

$$GPE = 0.5gd$$

$$EPE = \frac{20}{4}(1)$$



Finally :

$$KE = 0$$

$$GPE = 0$$

$$EPE = \frac{20}{4}(d-1)^2$$

$$\underline{0.5g} : 0.5gd + \frac{20}{4} = \frac{20}{4}(d^2 - 2d + 1)$$

$$0.5gd + 5 = 5(d^2 - 2d + 1)$$

$$5d^2 - 10d + 5 = 5 + 0 - 5gd$$

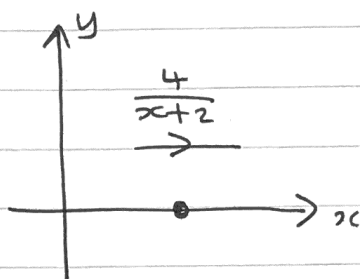
$$5d^2 - 10d - 0.5gd = 0$$

$$d(5d - 10 - 4.9) = 0$$

$$d \neq 0, \quad 5d = 14.9$$

$$\therefore d = \frac{14.9}{5} = \boxed{2.98 \text{ m}}$$

Q4a)



$$v = \frac{4}{x+2} = \frac{dx}{dt}$$

$$(x+2) \frac{dx}{dt} = 4$$

$$\therefore \int (x+2) dx = \int (4) dt$$

$$\frac{x^2}{2} + 2x = 4t + c$$

$$\underline{t=0, x=0} : 0 = c //$$

$$\therefore \frac{x^2}{2} + 2x = 4t //$$

$$\underline{t=2} : \frac{x^2}{2} + 2x = 8$$

$$\frac{x^2}{2} + 2x - 8 = 0$$

$$\underline{x=2} : x^2 + 4x - 16 = 0$$

By Quadratic Formula,  $x = -2 \pm 2\sqrt{5}$

$x > 0$  as P is always moving away from O.

$$\text{so } \boxed{x = -2 + 2\sqrt{5}}$$

$$= 2.47 \text{ m.}$$

b)  $v = 4(x+2)^{-1}$

$$\frac{dv}{dx} = -4(x+2)^{-2}$$

$$a = v \frac{dv}{dx} = v(-4(x+2)^{-2}) = \frac{4}{x+2} \times \frac{-4}{(x+2)^2}$$

$$a = \frac{-16}{(x+2)^3}$$

at  $t=2$ ,  $x = -2 + 2\sqrt{5}$  from (a).

$$\therefore a = \frac{-16}{(-2+2+2\sqrt{5})^3} = \underline{\underline{-0.18 \text{ ms}^{-2}}}$$

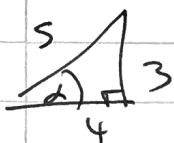
$$\text{so } |a| = 0.18 \text{ ms}^{-2}$$

Direction is towards O. (as  $a < 0$ )

Q5a) At A :  $KE = \frac{1}{2} M (\sqrt{gr})^2$   
 $GPE = 0$

At B :  $KE = \frac{1}{2} M v^2$   
 $GPE = Mgr(1 - \cos \alpha)$

C.O.E :  $\frac{Mgr}{2} = \frac{Mv^2}{2} + Mgr(1 - \cos \alpha)$



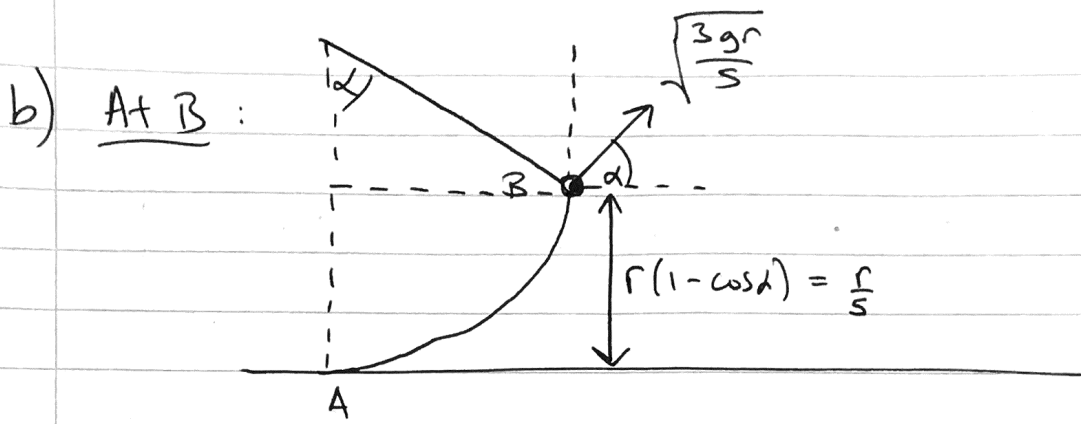
$\tan \alpha = \frac{3}{4} \quad \therefore \cos \alpha = \frac{4}{5}$

$$\text{so } \frac{gr}{2} = \frac{v^2}{2} + gr \left(1 - \frac{4}{5}\right)$$

$$gr = v^2 + \frac{2gr}{5}$$

$$v^2 = \frac{3gr}{5}$$

$$\therefore v = \sqrt{\frac{3gr}{5}} = \text{speed at B.}$$



$$\vec{u} = \sqrt{\frac{3gr}{5}} \cos \alpha = \frac{4}{5} \sqrt{\frac{3gr}{5}} \xrightarrow{r=0.4} \vec{u} = \frac{4}{5} \sqrt{\frac{6g}{25}}$$

$$u \uparrow = \sqrt{\frac{3gr}{5}} \sin \alpha = \frac{3}{5} \sqrt{\frac{3gr}{5}} \xrightarrow{r=0.4} u \uparrow = \frac{3}{5} \sqrt{\frac{6g}{25}}$$

Subst from B till ground:

$$\left. \begin{array}{l} \uparrow S = -\frac{0.4}{5} \\ u = \frac{3}{5} \sqrt{\frac{6g}{25}} \\ v = \\ a = -g \\ t = \end{array} \right\} \begin{array}{l} s = ut + \frac{1}{2} at^2 \\ -\frac{2}{25} = \frac{3}{5} t \sqrt{\frac{6g}{25}} - \frac{g}{2} t^2 \\ -0.08 = 0.9202t - 4.9t^2 \end{array}$$

$$4.9t^2 - 0.9202t - 0.08 = 0$$

By Quadratic formula,  $t = 0.252$ ,  $-0.0647$ .  
↑  
reject ( $t \geq 0$ )

so M takes 0.252s to reach e

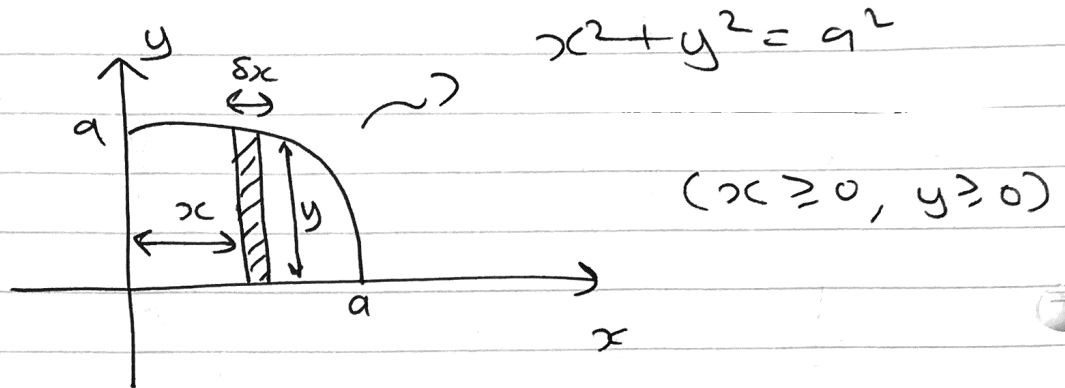
now consider horizontal motion of M,

$$\vec{s} = ut : \vec{BC} = \frac{4}{5} \sqrt{\frac{6g}{25}} \times 0.252 \approx 0.309 \text{ m}$$

$$\text{so } AC = r \sin \alpha + 0.309$$

$$\approx 0.4\left(\frac{3}{5}\right) + 0.309 \approx \boxed{0.55\text{m}}$$

Q6a)



split up this lamina into thin vertical strips of thickness  $\delta x$ ,

$$\text{mass of one strip} = \delta m = \rho \times \text{area} = \rho y \delta x.$$

$$\text{distance of c.o.m of one strip from } y\text{-axis} = x$$

$$\therefore m_i x_i = \rho x y \delta x //$$

$$\text{Total mass of lamina} = \rho \times \left(\frac{\pi a^2}{4}\right) = \frac{\rho \pi a^2}{4}.$$

$$\text{recall from M2 that } \bar{x} \sum m_i = \sum m_i x_i$$

$$\therefore \bar{x} \left(\frac{\rho \pi a^2}{4}\right) = \sum_{x=0}^a \rho x y \delta x$$

$$\lim_{\delta x \rightarrow 0} \sum_{x=0}^a \rho x y \delta x = \rho \int_0^a (x y) dx$$



$$p \int_0^a [2cy] dx = p \int_0^a [x] [\sqrt{a^2 - x^2}] dx$$

By Pattern.

$$= p \left[ -\frac{1}{2} \left( \frac{(a^2 - x^2)^{3/2}}{\frac{3}{2}} \right) \right]_0^a$$

$$= \left[ -\frac{1}{2} p \left[ \frac{2}{3} \right] [a^2 - x^2]^{3/2} \right]_0^a$$

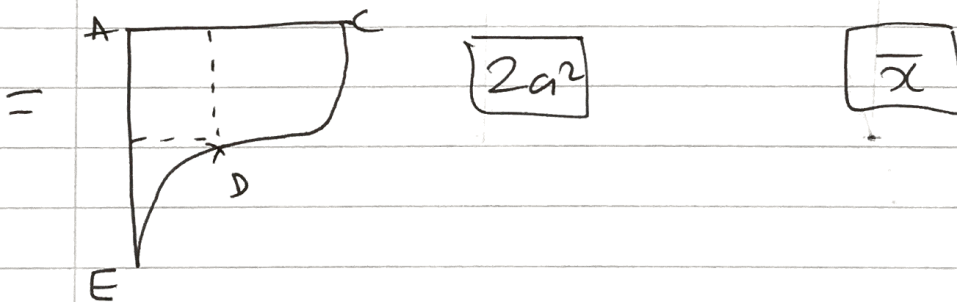
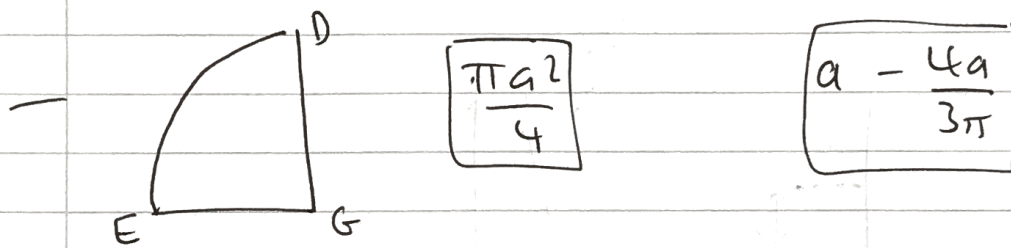
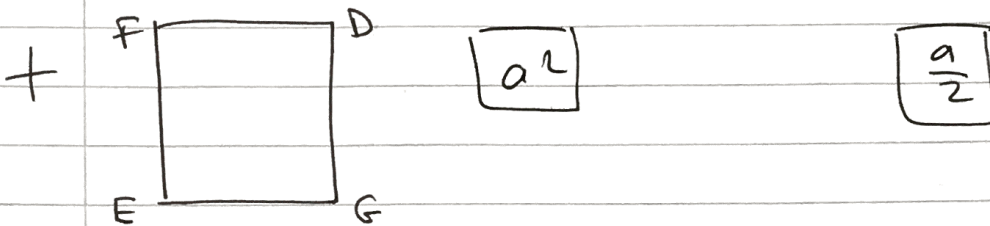
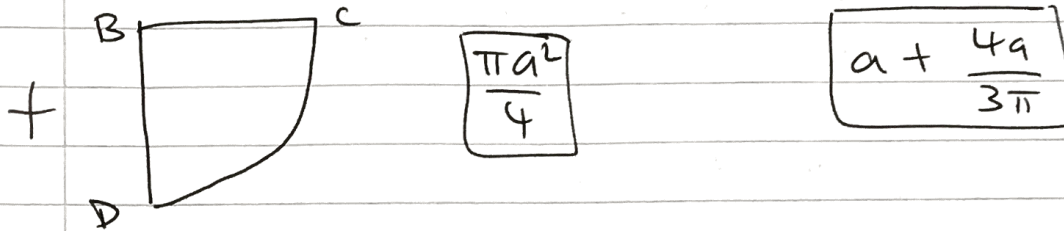
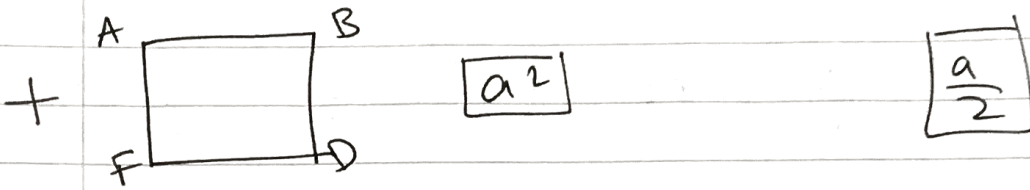
$$= \left[ -\frac{p}{3} (a^2 - x^2)^{3/2} \right]_0^a = [0] + \frac{p}{3} [a^2]^{3/2}$$

$$= \frac{p}{3} a^3 //$$

$$\therefore \pi \left( \frac{p\pi a^2}{4} \right) = \frac{pa^3}{3}$$

$$\Rightarrow \pi = \frac{4a^3 p}{3\pi a^2 p} = \frac{4a}{3\pi} = \text{distance from each edge.}$$

b) Shape      Mass      Distance of c.o.m from AE



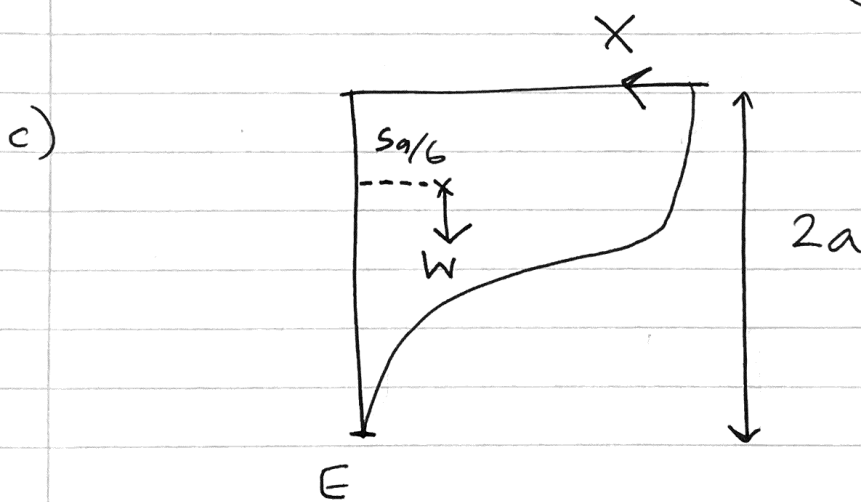
taking moments about side AE...

$$a^2 \left( \frac{a}{2} \right) + \frac{\pi g x}{4} \left( a + \frac{4a}{3\pi} \right) + a^2 \left( \frac{a}{2} \right) - \frac{\pi a^2}{4} \left( a - \frac{4a}{3\pi} \right) = 2a^2 \bar{x}$$

$$\Rightarrow a + \frac{\pi}{4} \left( a + \frac{4a}{3\pi} - a + \frac{4a}{3\pi} \right) = 2\bar{x}$$

$$\Rightarrow a + \frac{\pi}{4} \left( \frac{8a}{3\pi} \right) = 2\bar{x}$$

$$\Rightarrow a + \frac{2a}{3} = \bar{x} = \boxed{\frac{5a}{6}}$$



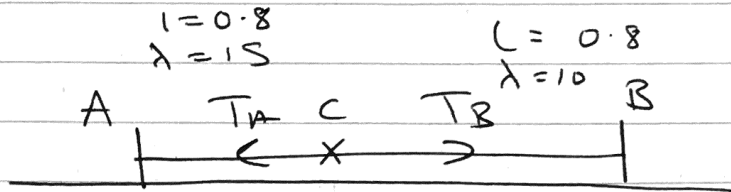
$X$  must act to the left to counteract the turning effect of the weight  $W$  since the entire lamina is in equilibrium.

$$\underline{M(E)} : X(2a) = W \left( \frac{5a}{6} \right)$$

$$X = \frac{\frac{5}{6}W}{2} \rightarrow X = \frac{5W}{12}$$

We take moments about E as this is where the axis passes through - we can then ignore the forces exerted by the axis on the lamina allowing us to deal only with W and X.

(7a)



$$T_A = T_B$$

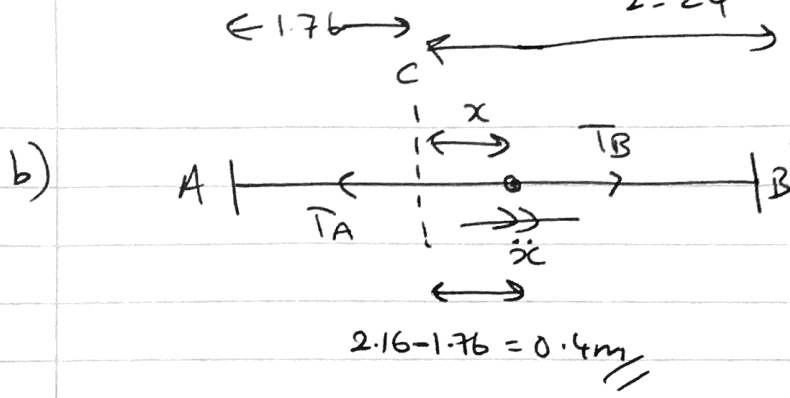
$$\frac{15}{0.8} (AC - 0.8) = \frac{10}{0.8} (4 - AC - 0.8)$$

$$\frac{75}{4} (AC - 0.8) = \frac{25}{2} (3.2 - AC)$$

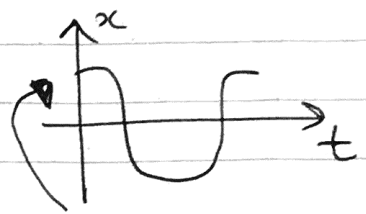
$$\frac{75}{4} AC - 15 = 40 - \frac{25}{2} AC$$

$$\left( \frac{75}{4} + \frac{25}{2} \right) AC = 55$$

$$\therefore AC = \frac{55}{\frac{125}{4}} = \boxed{1.76\text{m}}$$



P starts at an endpoint  
so  $x = a \cos \omega t$  applies



$\rightarrow +$   
N2L(P):  $T_B - T_A = 0.2\ddot{x}$

hence  $x$  is max at  $t=0$ . so  $x$  is positive in the direction CB.  
so  $\ddot{x}$  is also positive in the direction CB.

$\Rightarrow \frac{10}{0.8} (2.24 - x - 0.8) = T_B$

$\Rightarrow \frac{15}{0.8} (1.76 + x - 0.8) = T_A$

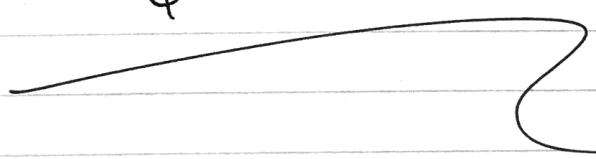
$\Rightarrow 12.5(1.44 - x) - 18.75(0.96 + x) = 0.2\ddot{x}$

$\Rightarrow 18 - 12.5x - 18 - 18.75x = 0.2\ddot{x}$

$\Rightarrow -\frac{125}{4}x = 0.2\ddot{x}$

$\Rightarrow -\frac{625}{4}x = \ddot{x}$

hence P moves with S.H.M



c) at C, speed is maximum.

$$v_{\max} = a\omega = 0.4 \times \sqrt{\frac{625}{4}} = \boxed{5 \text{ m/s}}$$

d)  $x = 0.4 \cos\left(t \sqrt{\frac{625}{4}}\right)$

$$\dot{x} = -0.4 \sqrt{\frac{625}{4}} \sin\left(t \sqrt{\frac{625}{4}}\right) = v_{//}$$

$$-2 = -0.4 \sqrt{\frac{625}{4}} \sin\left(t \sqrt{\frac{625}{4}}\right)$$

$$\frac{2}{0.4 \sqrt{\frac{625}{4}}} = \sin\left(t \sqrt{\frac{625}{4}}\right) = \frac{2}{5}$$

the first instance when the speed will be 2 m/s will be when P is moving in the direction BC so v will be -2 ms<sup>-1</sup>.

$$t \sqrt{\frac{625}{4}} = \sin^{-1}\left(\frac{2}{5}\right)$$

$$\therefore t = \frac{\sin^{-1}\left(\frac{2}{5}\right)}{\sqrt{\frac{625}{4}}} = \boxed{0.033 \text{ s}}$$