

Version 1.0



General Certificate of Education (A-level)
June 2013

Mathematics

MM03

(Specification 6360)

Mechanics 3

Final

Mark Scheme

Mark schemes are prepared by the Principal Examiner and considered, together with the relevant questions, by a panel of subject teachers. This mark scheme includes any amendments made at the standardisation events which all examiners participate in and is the scheme which was used by them in this examination. The standardisation process ensures that the mark scheme covers the students' responses to questions and that every examiner understands and applies it in the same correct way. As preparation for standardisation each examiner analyses a number of students' scripts: alternative answers not already covered by the mark scheme are discussed and legislated for. If, after the standardisation process, examiners encounter unusual answers which have not been raised they are required to refer these to the Principal Examiner.

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Key to mark scheme abbreviations

M	mark is for method
m or dM	mark is dependent on one or more M marks and is for method
A	mark is dependent on M or m marks and is for accuracy
B	mark is independent of M or m marks and is for method and accuracy
E	mark is for explanation
✓ or ft or F	follow through from previous incorrect result
CAO	correct answer only
CSO	correct solution only
AWFW	anything which falls within
AWRT	anything which rounds to
ACF	any correct form
AG	answer given
SC	special case
OE	or equivalent
A2,1	2 or 1 (or 0) accuracy marks
-x EE	deduct x marks for each error
NMS	no method shown
PI	possibly implied
SCA	substantially correct approach
c	candidate
sf	significant figure(s)
dp	decimal place(s)

No Method Shown

Where the question specifically requires a particular method to be used, we must usually see evidence of use of this method for any marks to be awarded.

Where the answer can be reasonably obtained without showing working and it is very unlikely that the correct answer can be obtained by using an incorrect method, we must award **full marks**. However, the obvious penalty to candidates showing no working is that incorrect answers, however close, earn **no marks**.

Where a question asks the candidate to state or write down a result, no method need be shown for full marks.

Where the permitted calculator has functions which reasonably allow the solution of the question directly, the correct answer without working earns **full marks**, unless it is given to less than the degree of accuracy accepted in the mark scheme, when it gains **no marks**.

Otherwise we require evidence of a correct method for any marks to be awarded.

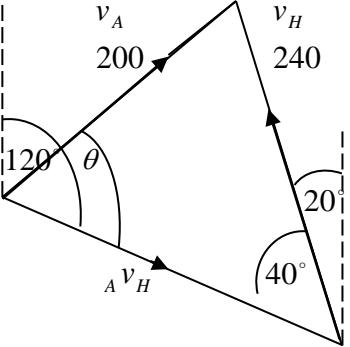
Q	Solution	Marks	Total	Comments
1	<p>Use of Impulse-momentum principle</p> $\int_{(0)}^{(T)} (3t + 1) dt = 2(5) - 2(1)$ $\left[\frac{3}{2}t^2 + t \right]_{(0)}^{(T)} = (8)$ $3T^2 + 2T - 16 = 0$ $(3T + 8)(T - 2) = 0$ <p>or $T = \frac{-2 \pm \sqrt{4 - 4(3)(-16)}}{2(3)}$</p> <p>$(T = -\frac{8}{3}$ unacceptable, not in the interval $0 \leq t \leq 3$)</p> $\underline{T = 2}$	<p>M1</p> <p>A1</p> <p>A1</p> <p>A1</p> <p>m1</p> <p>A1</p>	6	<p>$\int_{(0)}^{(T)} (3t + 1) dt = \pm 2(5) \pm 2(1)$</p> <p>Condone sign error for M1 A1 for all correct</p> <p>Correct integration, PI by the correct quadratic</p> <p>Correct use of correct limits and rearrangement</p> <p>Solution of their quadratic, correct attempt needed</p>
	Total		6	
2	<p>$[P] = MLT^{-2} \cdot L \cdot T^{-1} = ML^2T^{-3}$</p> <p>$[mgv \sin \theta] = M \cdot LT^{-2} \cdot LT^{-1} = ML^2T^{-3}$</p> <p>$[Rv] = MLT^{-2} \cdot LT^{-1} = ML^2T^{-3}$</p> <p>$\left[\frac{1}{2}mv^3 \frac{\sin \theta}{h} \right] = M \cdot L^3T^{-3} \cdot L^{-1} = ML^2T^{-3}$</p> <p>The formula is dimensionally consistent</p>	<p>B1</p> <p>B1</p> <p>B1</p> <p>B1</p> <p>B1</p> <p>E1</p>		<p>For correct unsimplified dimensions of quantities</p> <p>All simplifications correct</p> <p>Dependent on the last B1</p>
	Total		6	

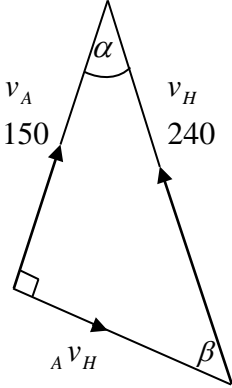
Q	Solution	Marks	Total	Comments
3(a)	$x = ut \cos \theta$	M1	6	Condone + g for M1
	$t = \frac{x}{u \cos \theta}$	A1		
	$y = -\frac{1}{2}gt^2 + ut \sin \theta$	M1		
	$y = -\frac{1}{2}gt^2 + ut \sin \theta$	A1		
	$y = -\frac{1}{2}g\left(\frac{x}{u \cos \theta}\right)^2 + u\left(\frac{x}{u \cos \theta}\right)\sin \theta$	m1		
	$y = -\frac{gx^2}{2u^2 \cos^2 \theta} + \frac{x \sin \theta}{\cos \theta}$			
	$y = -\frac{gx^2}{2u^2}(1 + \tan^2 \theta) + x \tan \theta$	A1		
(b)(i)	$0.5 = -\frac{9.8(5)^2}{2(8)^2}(1 + \tan^2 \theta) + 5 \tan \theta$	M1	5	Correctly substituting for x , y, u and g into their equation of trajectory All correct, condone decimal approximation. OE exact quadratic in $\tan \theta$ PI by the values of $\tan \theta$
	$245 \tan^2 \theta - 640 \tan \theta + 309 = 0$	A1		
	$\tan \theta = \frac{640 \pm \sqrt{(-640)^2 - 4(245)(309)}}{2(245)}$	m1		
	$\tan \theta = 1.973(004)$, $0.6392(41)$ $\theta = 63.12^\circ$, 32.58° $\theta = 63.1^\circ$, 32.6°	A1		
(ii)	$\dot{y} = -9.8\left(\frac{5}{8 \cos 63.1^\circ}\right) + 8 \sin 63.1^\circ$ OE	M1	4	AG Must see the above or more accurate values Condone +9.8 for M1. PI by correct angle in a statement Have to see “horizontal” or “vertical” or diagram
	$(\dot{y} = -6.4035)$			
	$\dot{x} = 8 \cos 63.1^\circ$	M1		
	$(\dot{x} = 3.6195)$			
	$\tan^{-1} \frac{6.4(035)}{3.6(195)} (= 61^\circ)$ OE	m1		
	Direction : 61° to the horizontal or 29° to the vertical	A1		

Q	Solution	Marks	Total	Comments
3(b)(ii)	Alternative: $\frac{dy}{dx} = -\frac{2gx}{2u^2}(1 + \tan^2 \theta) + \tan \theta$ $= -\frac{2 \times 9.8 \times 5}{2 \times 8^2}(1 + \tan^2 63.1^\circ) + \tan 63.1^\circ$ $= -1.7692$ $\tan^{-1}(-1.7692) = -60.52368^\circ$ Direction: 61° to the horizontal or 29° to the vertical	(M1) (A1) (m1) (A1)		
(c)	The ball is a particle, or No air resistance, or The ball does not spin	B1	1	
	Total		16	
4(a)	$m(4u) + 3m(2u) = mv_A + 3mv_B$ $\frac{v_B - v_A}{4u - 2u} = e$ $\left(\begin{array}{l} v_A + 3v_B = 10u \\ v_B - v_A = 2ue \\ 4v_B = 2ue + 10u \end{array} \right)$ $v_B = \frac{u}{2}(e + 5)$ $\left(v_A = \frac{u}{2}(e + 5) - 2ue \right)$ $v_A = \frac{u}{2}(-3e + 5)$	M1 A1 M1 A1 A1 A1	6	M1 for four correct momentum terms with any signs. A1 for all correct M1 for correct terms for any signs, A1 for all correct. OE, simplified OE, simplified
(b)	$e \leq 1 \Rightarrow v_B \leq \frac{u}{2}(1 + 5)$ $\Rightarrow v_B \leq 3u$	M1 A1	2	Use of $e \leq 1$ (OE) needed FT their v_B
(c)	$(I =) 3m \cdot \frac{u}{2} \left(\frac{2}{3} + 5 \right) - 3m \cdot 2u$ $= \frac{5mu}{2}$ or $2.5mu$	M1 A1F A1	3	M1 for a difference of two momentums FT their velocity from part (a) A1F for their 'Final B – Initial B'
	Total		11	

Q	Solution	Marks	Total	Comments
5(a)	\perp to plane $y = ut \sin \alpha - \frac{1}{2}gt^2 \cos \theta$	M1	4	For M1, $\sin \alpha$ and $\cos \theta$ must be in the correct terms but accept $+g$. Accept $+g$ for m1. OE
	$y = ut \sin \alpha - \frac{1}{2}gt^2 \cos \theta$	A1		
	$uT \sin \alpha - \frac{1}{2}gT^2 \cos \theta = 0$	m1		
	$u = \frac{Tg \cos \theta}{2 \sin \alpha}$	A1		
(b)	t or $T = \frac{2u \sin \alpha}{g \cos \theta}$	B1	6	For M1, $\cos \alpha$ and $\sin \theta$ must be in the correct terms but accept $-g$. Elimination of t substituting their expression into their equation for x . OE single correct fraction in factorised form AG Sight of the above line needed
	\parallel to plane $x = ut \cos \alpha + \frac{1}{2}gt^2 \sin \theta$	M1		
	$x = ut \cos \alpha + \frac{1}{2}gt^2 \sin \theta$	A1		
	$(\overline{OP} =) u \left(\frac{2u \sin \alpha}{g \cos \theta} \right) \cos \alpha + \frac{1}{2}g \left(\frac{2u \sin \alpha}{g \cos \theta} \right)^2 \sin \theta$	m1		
	$\left(= \frac{2u^2 \sin \alpha \cos \alpha}{g \cos^2 \theta} + \frac{2u^2 \sin^2 \alpha \sin \theta}{g \cos^2 \theta} \right)$			
	$= \frac{2u^2 \sin \alpha (\cos \alpha \cos \theta + \sin \alpha \sin \theta)}{g \cos^2 \theta}$	m1		
$= \frac{2u^2 \sin \alpha \cos(\alpha - \theta)}{g \cos^2 \theta}$	A1			
	Total		10	

Q	Solution	Marks	Total	Comments
6	(Let $v_B = a\mathbf{i} - b\mathbf{j}$)			
	$\frac{a}{b} = \frac{3}{2}$	M1		Allow sign error
	$\frac{a}{b} = \frac{3}{2}$	A1		OE
	(Squares are smooth \Rightarrow j component \Rightarrow) $b = 3$	B1		
	$a = \frac{9}{2}$	A1	4	AG
	$\left(v_B = \frac{9}{2}\mathbf{i} - 3\mathbf{j} \right)$			
	(b) (C.L.M. along the line of centres:)			
	$4(4) - 2(2) = 4(v_A) + 2\left(\frac{9}{2}\right)$	M1		OE, No sign errors
	$v_A = \frac{3}{4}$	A1		
	(Restitution along the line of centres:)			
$e = \frac{-\frac{3}{4} + \frac{9}{2}}{4 + 2}$ OE	M1 A1		M1 for correct terms, A0 for sign error	
$e = \frac{5}{8}$	A1	5		
(c) (I = Change in momentum of B along the line of centres)				
$= 2\left(\frac{9}{2}\mathbf{i}\right) - 2(-2\mathbf{i})$	M1		Allow sign error and missing \mathbf{i}	
$= 13\mathbf{i}$	A1		A0 for magnitude or $-13\mathbf{i}$	
Ns or kg m s^{-1}	B1	3		
	Total		12	

Q	Solution	Marks	Total	Comments
7(a)(i)	 <p data-bbox="247 683 411 757"> $\frac{\sin \theta}{240} = \frac{\sin 40}{200}$ </p> <p data-bbox="247 806 542 840"> $\theta = 50.47483^\circ$ or 50.5° </p> <p data-bbox="247 900 510 936">Bearing of $v_A = 069.5^\circ$</p>	<p data-bbox="794 414 833 448">B1</p> <p data-bbox="794 515 833 548">B1</p> <p data-bbox="794 705 833 739">M1</p> <p data-bbox="794 806 833 840">A1</p> <p data-bbox="794 907 833 940">A1</p>	<p data-bbox="917 907 941 940">5</p>	<p data-bbox="997 414 1476 448">Correct diagram with or without arrows.</p> <p data-bbox="997 481 1436 560">40° marked correctly, PI by correct method.</p> <p data-bbox="997 705 1444 784">Correct sine rule allowing their angle opposite 200 in their diagram.</p> <p data-bbox="997 806 1428 840">AWRT 50.5°, PI by correct bearing</p> <p data-bbox="997 907 1149 940">Allow 69.5°</p>
(a)(ii)	<p data-bbox="247 996 542 1198"> $\frac{{}_A v_H}{\sin(180^\circ - 40^\circ - 50.5^\circ)} = \frac{200}{\sin 40^\circ} \text{ or } \frac{240}{\sin 50.5^\circ}$ ${}_A v_H = 311.13408 \text{ or } 311$ </p> <p data-bbox="247 1243 478 1321"> $\text{Time} = \frac{20}{311.13408}$ </p> <p data-bbox="263 1366 670 1400"> $(= 0.0642809 \text{ hours}) = 3.86 \text{ min}$ </p>	<p data-bbox="794 1075 833 1108">M1</p> <p data-bbox="794 1164 845 1198">A1F</p> <p data-bbox="794 1265 833 1299">M1</p> <p data-bbox="794 1366 845 1400">A1F</p>	<p data-bbox="917 1366 941 1400">4</p>	<p data-bbox="997 1075 1476 1108">Allow using their angle from part (a)(i).</p> <p data-bbox="997 1164 1356 1198">FT their angle from part (a)(i)</p> <p data-bbox="997 1265 1468 1299">PI by correct answer. Allow their ${}_A v_H$.</p> <p data-bbox="997 1366 1149 1400">3sf required</p>

Q	Solution	Marks	Total	Comments
7(b)	 <p data-bbox="244 757 676 875"> $\cos \alpha = \frac{150}{240}$ or $\sin \beta = \frac{150}{240}$ $\alpha = 51.3^\circ$ or $\beta = 38.7^\circ$ </p> <p data-bbox="244 931 437 965">Bearing: 031.3°</p>	<p data-bbox="794 349 836 383">M1</p> <p data-bbox="794 483 836 517">A1</p> <p data-bbox="794 775 836 808">M1</p> <p data-bbox="794 842 836 875">A1</p> <p data-bbox="794 943 836 976">A1</p>	<p data-bbox="916 943 940 976">5</p>	<p data-bbox="999 349 1469 416">Right-angled triangle with 240 and 150 marked.</p> <p data-bbox="999 483 1225 517">Correct orientation</p> <p data-bbox="999 842 1251 875">PI by correct bearing</p> <p data-bbox="999 943 1150 976">Allow 31.3°</p>
	Total		14	
	TOTAL		75	