

Eigenvectors and Eigenvalues

If a matrix A transforms a non-zero vector v such that the output is a scalar multiple of v ,

$$Av = \lambda v,$$

then v is called an **eigenvector** of matrix A , with λ its corresponding **eigenvalue**. Eigenvectors are special to a matrix transformation, as their direction is unchanged during a linear transformation – they get stretched or squashed. The equation above is called the **eigenvalue equation**. Invariant lines of a transformation are parallel to eigenvectors. To find the eigenvectors and corresponding eigenvalues of a given matrix A ,

$$Av = \lambda v \Rightarrow Av = \lambda Iv \\ \Rightarrow (A - \lambda I)v = 0$$

where I is the identity matrix. For this to be true for a non-zero v , $(A - \lambda I)$ must be singular, i.e.

$$\det(A - \lambda I) = 0.$$

This is the **characteristic equation** of A and is a polynomial in λ . The roots are the eigenvalues of A . The respective eigenvectors can then be found by plugging each root λ back into the equation.

Example: Find the eigenvalues and eigenvectors of $A = \begin{pmatrix} 0 & 1 \\ -2 & -3 \end{pmatrix}$.

Find and solve the characteristic equation to obtain the eigenvalues	$\det(A - \lambda I) = \begin{vmatrix} 0 - \lambda & 1 \\ -2 & -3 - \lambda \end{vmatrix} \\ = (-\lambda)(-3 - \lambda) - (-2)(1) = \lambda^2 + 3\lambda + 2 = 0 \Rightarrow \lambda = -1, -2$
Find the eigenvector for λ_1 . Any multiple of this vector is also an eigenvector.	When $\lambda = -1$, $Av = \lambda v \Rightarrow \begin{pmatrix} 0 & 1 \\ -2 & -3 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = -1 \begin{pmatrix} x \\ y \end{pmatrix}$ Equating the top and bottom elements from either side $\begin{aligned} 0x + y &= -x & x + y &= 0 \\ -2x - 3y &= -y & -2x - 2y &= 0 \end{aligned}$ Both equations give the same information and accept any solution if $y = -x \therefore v = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$ is an acceptable eigenvector.
Find the eigenvector for λ_2 . Any multiple of this vector is also an eigenvector.	When $\lambda = -2$, $Av = \lambda v \Rightarrow \begin{pmatrix} 0 & 1 \\ -2 & -3 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = -2 \begin{pmatrix} x \\ y \end{pmatrix}$ Equating the top and bottom elements from either side $\begin{aligned} 0x + y &= -2x & 2x + y &= 0 \\ -2x - 3y &= -2y & -2x - y &= 0 \end{aligned}$ Both equations give the same information and accept any solution if $y = -2x \therefore v = \begin{pmatrix} 1 \\ -2 \end{pmatrix}$ is an acceptable eigenvector.

If A were a 3×3 matrix, the characteristic equation would be a cubic equation and there would be up to 3 eigenvalues and eigenvectors. A **normalised eigenvector** is an eigenvector of length 1.

If v is an eigenvector, its normalised vector is given by $\hat{v} = \frac{v}{|v|}$, where $|v|$ is the length of v .

Diagonalisation

A square matrix is **diagonal** if all elements that are not on its **leading diagonal** are zero. The leading diagonal is the line of elements from the **top left to bottom right** of a square matrix.

$\begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix}$	$\begin{pmatrix} -7 & 0 & 0 \\ 0 & e^{\pi i} & 0 \\ 0 & 0 & 1 \end{pmatrix}$	$\begin{pmatrix} 0 & 0 & 9 \\ 0 & 4 & 0 \\ 1 & 0 & 0 \end{pmatrix}$	$\begin{pmatrix} 0 & 0 & 0 \\ 2 & 0 & 0 \\ 0 & 6 & 0 \end{pmatrix}$
Diagonal	Diagonal	Not Diagonal (The leading diagonal is not the only collection of non-zero elements)	Not Diagonal (The leading diagonal is not filled in)

Most square matrices can be transformed into a diagonal matrix. This process is called **diagonalisation**. The diagonal entries of this matrix are the eigenvalues of the original matrix.

Example: Diagonalise $A = \begin{pmatrix} 1 & 2 & 0 \\ 0 & 3 & 0 \\ 2 & -4 & 2 \end{pmatrix}$ into a diagonal matrix D , such that $D = P^{-1}AP$, where P is to be found.

Find and solve the characteristic equation to obtain the eigenvalues.	$\det(A - \lambda I) = \begin{vmatrix} 1 - \lambda & 2 & 0 \\ 0 & 3 - \lambda & 0 \\ 2 & -4 & 2 - \lambda \end{vmatrix} \\ = (1 - \lambda)(3 - \lambda)(2 - \lambda) - (0)(-4) - (2)(0)(2 - \lambda) - (0)(2) \\ + (0)((-4) - (2)(3 - \lambda)) \\ = (1 - \lambda)(\lambda^2 - 5\lambda + 6) = -(\lambda - 1)(\lambda - 2)(\lambda - 3) \Rightarrow \lambda = 1, 2, 3$
Find the eigenvector for λ_1 .	When $\lambda = 1$, $Av = \lambda v \Rightarrow \begin{pmatrix} 1 & 2 & 0 \\ 0 & 3 & 0 \\ 2 & -4 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$ $\begin{aligned} x + 2y &= x & y &= 0 \\ 3y &= y & y &= 0 \\ 2x - 4y + 2z &= z & z &= y - 2x \end{aligned}$ These equations accept any solution if $z = -2x \therefore v = \begin{pmatrix} 1 \\ 0 \\ -2 \end{pmatrix}$
Find the eigenvector for λ_2 .	When $\lambda = 2$, $Av = \lambda v \Rightarrow \begin{pmatrix} 1 & 2 & 0 \\ 0 & 3 & 0 \\ 2 & -4 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = 2 \begin{pmatrix} x \\ y \\ z \end{pmatrix}$ $\begin{aligned} x + 2y &= 2x & x &= 2y \\ 3y &= 2y & y &= 0 \\ 2x - 4y + 2z &= 2z & x &= 2y \end{aligned}$ These equations accept any solution if $x = y = 0 \therefore v = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$
Find the eigenvector for λ_3 .	When $\lambda = 3$, $Av = \lambda v \Rightarrow \begin{pmatrix} 1 & 2 & 0 \\ 0 & 3 & 0 \\ 2 & -4 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = 3 \begin{pmatrix} x \\ y \\ z \end{pmatrix}$ $\begin{aligned} x + 2y &= 3x & x &= y \\ 3y &= 3y & y &= y \\ 2x - 4y + 2z &= 3z & z &= 2x - 4y \end{aligned}$ These equations accept any solution if $x = y, z = 2x - 4y$. Taking $x = y = 1, v = \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix}$
P is the matrix of eigenvectors. D is the diagonal matrix of eigenvalues, in the same order as their eigenvectors in P .	$P = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 0 & 1 \\ -2 & 1 & -2 \end{pmatrix}, \quad D = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{pmatrix}$

There is a relationship between any A , P and D in general:

$$D = P^{-1}AP.$$

If $A = A^T$, its entries are a reflection along the leading diagonal. Such a matrix is called **symmetric**, and its **normalised eigenvectors are always orthogonal to each other**. A matrix made of orthogonal vectors is called an **orthogonal matrix**. Orthogonal matrices have the property that **their transpose is their inverse** and vice versa. In this case, **orthogonal diagonalisation** is used.

If A is a symmetric matrix, $D = P^TAP$ since if A is symmetric, P is orthogonal. Hence, $P^T = P^{-1}$.

Example: Diagonalise $A = \begin{pmatrix} 3 & 2 \\ 2 & 3 \end{pmatrix}$ by finding a matrix P and diagonal matrix D such that $D = P^{-1}AP$.

Find and solve the characteristic equation to obtain the eigenvalues.	$\det(A - \lambda I) = \begin{vmatrix} 3 - \lambda & 2 \\ 2 & 3 - \lambda \end{vmatrix} \\ = (3 - \lambda)^2 - 2^2 = -\lambda^2 - 6\lambda + 5 = 0 = (\lambda - 1)(5 - \lambda) = 0 \Rightarrow \lambda = 1, 5$
Since A is symmetric, use orthogonal diagonalisation. Find the normalised eigenvector for λ_1 .	When $\lambda = 1$, $Av = \lambda v \Rightarrow \begin{pmatrix} 3 & 2 \\ 2 & 3 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix}$ Equating elements from either side, $\begin{aligned} 3x + 2y &= x & x + y &= 0 \\ 2x + 3y &= y & x + y &= 0 \end{aligned}$ These equations accept any solution if $y = -x, \therefore v = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$ $\therefore \hat{v} = \frac{1}{\sqrt{1^2 + (-1)^2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 1/\sqrt{2} \\ -1/\sqrt{2} \end{pmatrix}$
Find the normalised eigenvector for λ_2 .	When $\lambda = 5$, $Av = \lambda v \Rightarrow \begin{pmatrix} 3 & 2 \\ 2 & 3 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 5 \begin{pmatrix} x \\ y \end{pmatrix}$ Equating elements from either side, $\begin{aligned} 3x + 2y &= 5x & -x + y &= 0 \\ 2x + 3y &= 5y & x - y &= 0 \end{aligned}$ These equations accept any solution if $y = x, \therefore v = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ $\therefore \hat{v} = \frac{1}{\sqrt{1^2 + 1^2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{pmatrix}$
P is the matrix of normalised eigenvectors, and D is the diagonal matrix of eigenvalues, as before.	$P = \begin{pmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ -1/\sqrt{2} & 1/\sqrt{2} \end{pmatrix}, \quad D = \begin{pmatrix} 1 & 0 \\ 0 & 5 \end{pmatrix}$

Diagonal matrices are easier to perform long calculations with. For any diagonal $k \times k$ matrix D ,

$$\text{if } D = \begin{pmatrix} a_1 & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & 0 & a_k \end{pmatrix}, \quad D^n = \begin{pmatrix} a_1^n & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & 0 & a_k^n \end{pmatrix}.$$

Cayley-Hamilton Theorem

This theorem states that every square matrix A is a solution to its own characteristic equation. Plugging a matrix into a polynomial feels unnatural, but it works by considering I as 1.

Example: Verify the Cayley-Hamilton Theorem on $A = \begin{pmatrix} 0 & 1 \\ -2 & -3 \end{pmatrix}$ and use it to find its inverse.

Find the characteristic equation of A .	$\det(A - \lambda I) = \begin{vmatrix} 0 - \lambda & 1 \\ -2 & -3 - \lambda \end{vmatrix} = 0 = \lambda(\lambda + 3) + 2 = \lambda^2 + 3\lambda + 2 = 0$
Use the Cayley-Hamilton Theorem.	$A^2 + 3A + 2I = 0 \xrightarrow{\text{Multiply by } A^{-1}} A + 3I + 2A^{-1} = 0$
Rearrange for A^{-1} .	$A^{-1} = -\frac{1}{2}A - \frac{3}{2}I = -\frac{1}{2} \begin{pmatrix} 0 & 1 \\ -2 & -3 \end{pmatrix} - \frac{3}{2} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} -3/2 & -1/2 \\ 1 & 0 \end{pmatrix}$

